Druid: Use of Crossing-State Equivalence Classes for Rapid Relabeling of Knot-Diagrams Representing 21/2 D Scenes

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Introduction

In our earlier work, we developed *Druid* [2], a drawing program which permits construction of $2\frac{1}{2}$ D scenes. *A* $2\frac{1}{2}$ D scene is fundamentally 2D, but represents relative depths of surfaces. Conventional drawing programs use a layered representation which limits them to DAG-based scenes (Fig 1).

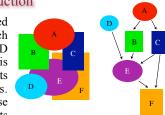


Figure 1. A surface DAG typical of a conventional layer-based drawing program.



Druid represents $2\frac{1}{2}$ D scenes with a *labeled knot-diagram* (Fig. 2) [1], which assigns a *sign of occlusion* to every boundary (shown hashed), to state which side of the boundary the surface lies on, and a depth index to every boundary segment. This representation permits interwoven scenes.

Figure 2. A *labeled knot-diagram* representation permits scenes of interwoven surfaces.

A *legal labeling* is one in which every crossing honors the *labeling scheme* (Fig. 3), which specifies constraints on the relative depths at a crossing.

Three Labeling Methods

Occasionally, *Druid* must find a new legal labeling, *e.g.*, after a *surface-flip* user-interaction, in which the user inverts the relative depth ordering of two surfaces within an area of overlap (Fig. 5). It is desirable that the new labeling be a *minimum difference* labeling with respect to the labeling preceding the flip.

There are three methods for relabeling a figure:

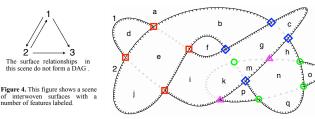
- 1. Perform a tree search (our original method).
- **2.** Perform the same search using equivalence classes as a search constraint.
- **3.** Maintain the equivalence classes without a search and deduce the resulting segment depth changes directly.

Although we have developed a number of search optimization techniques, *Druid's* capability using Method 1 remained limited due to long search times for complex drawings.

Definition of Concepts

In the following definitions, examples refer to Fig. 4.

- 2½ D scene a scene of surfaces (surfaces shown numbered) which may overlap or interweave, e.g., Figs. 1, 2, 4, 5, and 6.
- *Boundary segment* a section of a boundary joining two crossings.
- *Region* a partitioning of the canvas along boundary segments (regions shown lettered). Every region is covered by zero or more surfaces, *e.g.*, region *k* is covered by surfaces *1* and *3*.



- Superregion a set of contiguous regions covered by a single surface, *e.g.*, { *b*, *g*, *h*, *n* } for surface 2.
- *Shared superregion* the maximum superregion common to two surfaces, *e.g.*, { *g*, *m* } for surfaces *1* and *2*.
- **Corner of a shared superregion** a crossing where adjacent segments of a shared superregion's border belong to different surfaces, *e.g.*, corners for shared superregion $\{m, n\}$ of surfaces 2 and 3 are marked with green circles.

Crossing-State Equivalence Class

The corners of a shared superregion comprise the *crossing-state equivalence class* for that shared superregion. Notice that every crossing in a drawing is a corner of some shared superregion. Consequently, every crossing is a member of some crossing-state equivalence class. Crossing-state equivalence classes are marked with unique shapes/colors at the crossings in Fig 4.

Crossing-State Equivalence Class Rule

Let X and Y be the two surfaces whose boundaries intersect at a crossing. The crossing can only be in one of two states. Either X is above Y or Y is above X.

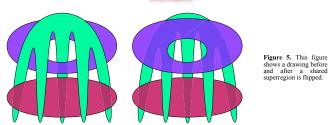
The Crossing-State Equivalence Class Rule states:

All crossings in a crossing-state equivalence class must be in the same state.

The rule is proven in [3].

Consider the superregion $\{m, n\}$ shared by surfaces 2 and 3. The only segment interior to the shared superregion is part of the boundary of surface 1. Therefore, surfaces 2 and 3 cannot change relative depth along that boundary segment. Thus, all corners of $\{m, n\}$ (marked with green circles) must be in the same state.

Results



Method	Crossing-state search space size
	2 ⁴⁰ (for 40 crossings)
	2 ⁷ (for 7 equivalence classes)
	N/A, <i>i.e.</i> , 0 (there is no search)

The *labeling space* consists of all crossing-state labelings crossed with all segment depth labelings. Table 1 only shows the crossing-state search space sizes for Fig. 5. Method 2 is

Table 1. Crossing-state search space sizes for the three relabeling methods applied to Fig. 5.

more efficient than Method 1 by a factor of 2^{33} , or 8,589,934,592. Method 3 is even better.

Table 2 shows relabeling running times for the flip shown in Fig. 5 on a 1.6GHz G5 PowerMac. We observe that Method 2 is adequate for most drawings. Method 3 can extend *Druid's* capability even further however.

Method	Time (secs)
1	45.19s
	.15s
	<.01s

Table 2. Relabeling running times for the three methods applied to Fig. 5.

Example



Figure 6. A fairly complex scene that our original system could not handle in reasonable running times. The new system performs very well, with response times on the order of a few seconds Subsequent surface-flips are instantaneous.

Fig. 6 shows a scene with 256

crossings and 64 equivalence classes.

Druid can find the equivalence

classes and label this figure from

scratch in 6.04 seconds. Method 1 fails to find any legal labeling in a

reasonable time (the search was

terminated after a few minutes).

Conclusions

In our earlier work, we developed *Druid*, a system for constructing interwoven $2\frac{1}{2}$ D scenes. Past versions of *Druid* relied on a tree search to find a new labeling following many user-interactions. Even with substantial optimization techniques, this search hindered *Druid*'s scalability.

We have discovered a topological trait of $2\frac{1}{2}$ D scenes which we call the crossing-state equivalence class rule. Exploitation of this trait can alleviate the need to search in some situations, and can dramatically reduce the search space in remaining situations that require a search. Thus, we have vastly extended the complexity of drawings that users of *Druid* can construct.

References

 Lance R. Williams. Perceptual Completion of Occluded Surfaces. Ph.D. dissertation. Univ. of Massachusetts at Amherst, 1994.

[2] Keith Wiley and Lance R. Williams. Representation of interwoven surfaces in 2½ D drawing. In CHI Proceedings, 2006.

[3] Keith Wiley and Lance R. Williams. Use of Crossing-State Equivalence Classes for Rapid Relabeling of Knot-Diagrams Representing 2½ D Scenes. CSUSC, 2006.

 $y \ge x$ $y \ge x + 1$ $y \ge x + 1$ y = x + 1 y = x +